# Infinite Task Learning with Vector-Valued RKHSs

Alex Lambert Joint work with R. Brault, Z. Szabo, M. Sangnier, F.d'Alché-Buc. September 13, 2018



# Motivation

- $(X, Y) \in \mathbb{R}^d \times \mathbb{R}$  random variables
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from *iid* copies  $(x_i, y_i)_{i=1}^n$ 

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Figure 1: Example of several quantile functions (toy dataset). 1/18

Minimize in *h* 

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Figure 2: Two independently learnt quantile estimations.

- Not adapted to the structure of the problem
- No way to recover other quantiles

## An example of task : Cost-Sensitive Classification

• Binary classification with asymetric loss function. Minimize

$$\mathsf{E}_{X,Y}\left[\left|\frac{\theta+1}{2}-\mathbb{1}_{\{-1\}}(Y)\right|\left|1-Yh(X)\right|_{+}\right]$$

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Figure 3: Independent cost-sensitive classification.

• No structure, No interpolation

## An example of task : Density Level Set Estimation

(Schölkopf et al., 2000) Given  $(x_i)_{i=1}^n$  iid and  $\theta \in (0, 1)$ , minimize for  $(h, t) \in \mathfrak{H}_k \times \mathbb{R}$ 

$$J(h,t) = \frac{1}{\theta n} \sum_{i=1}^{n} \max(0, t - h(x_i)) - t + \frac{1}{2} ||h||_{\mathcal{H}_{k}}^{2}$$

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#### $\theta$ -property of the decision function

The decision function should separate new data into two separate subsets with proportion  $\theta$  of outliers.

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- Create specific model constraints with prior knowledge of tasks

How to extend this to a continuum of tasks ?

# Proposed framework : learn function-valued functions

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$$x \mapsto (\theta \mapsto y)'$$

Goal : Learn a global function while preserving desired properties of the output function for each hyperparameter  $\theta$ .

# Supervised Learning Framework

ERM setting: minimize in  $h \in \mathcal{H} \subset \mathcal{F}(\mathcal{X}; \mathcal{F}(\Theta; \mathbb{R}))$  for a training set  $\mathcal{S} = (x_i, y_i)_{i=1}^n$  and  $\lambda > 0$ 

$$R_{\mathcal{S}}(h) = \sum_{i=1}^{n} V(y_i, h(x_i)) + \lambda \Omega(h)$$

where

$$V(y,h(x)) := \int_{\Theta} v(\theta, y, h(x)(\theta)) d\mu(\theta),$$

and  $\Omega(h)$  is a regularization term.

$$\widetilde{V}(y, h(x)) := \sum_{j=1}^{m} w_j v(\theta_j, y, h(x)(\theta_j))$$

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- No need to approximate too precisely

# Functional space ${\mathcal H}$

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Take two scalar kernels  $k_{\mathfrak{X}}: \mathfrak{X} \times \mathfrak{X} \to \mathbb{R}$  and  $k_{\Theta}: \Theta \times \Theta \to \mathbb{R}$ , construct

$$\mathsf{K}: \begin{cases} \mathfrak{X} \times \mathfrak{X} & \to \mathcal{L}(\mathcal{H}_{k_{\Theta}}) \\ x, z & \mapsto k_{\mathfrak{X}}(x, z) I_{\mathcal{H}_{k_{\Theta}}} \end{cases}$$

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Structure:  $\mathcal{H}_{\mathcal{K}} \simeq \mathcal{H}_{k_{\mathcal{K}}} \otimes \mathcal{H}_{k_{\Theta}}$  *i.e* 

$$\mathcal{H}_{\mathcal{K}} = \overline{\operatorname{span}} \{ k_{\mathcal{X}}(\cdot, x) \cdot k_{\Theta}(\cdot, \theta), (x, \theta) \in \mathcal{X} \times \Theta \}$$

# Optimization

Optimization problem:

$$\underset{h \in \mathcal{H}_{\kappa}}{\operatorname{arg\,min}} \quad \widetilde{R}_{\mathcal{S}}(h) + \lambda \|h\|_{\mathcal{H}_{\kappa}}^{2}, \quad \lambda > 0 \tag{1}$$

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(1)

#### **Representer Theorem**

Assume that the local loss function is a proper *l.s.c* function. Then, the solution  $h^*$  to the problem (1) is unique and verifies  $\forall (x, \theta) \in \mathfrak{X} \times \Theta$ 

$$h^*(x)(\theta) = \sum_{i=1}^n \sum_{j=1}^m \alpha_{ij} k_{\mathcal{X}}(x, x_i) k_{\Theta}(\theta, \theta_j)$$

for some  $(\alpha_{ij})_{i,j=1}^{n,m} \in \mathbb{R}^{n \times m}$ .

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Solved by L-BFGS-B + smoothing of the local loss.

- Complexity in  $O(\# iterations \cdot (n^2m + nm^2))$
- Smoothing à la Huber: infimal convolution with  $\|{\cdot}\|^2$

## Context of uniform stability in vv-RKHS (Kadri et al., 2015)

## Generalization bound

Let  $h^* \in \mathcal{H}_K$  be the solution of the problem above for the QR or CSC problem with QMC approximation. For a large class of kernels,

$$R(h^*) \leqslant \widetilde{R}_{\mathcal{S}}(h^*) + \mathcal{O}_{\mathsf{P}_{X,Y}}\left(\frac{1}{\sqrt{\lambda n}}\right) + \mathcal{O}\left(\frac{\log(m)}{\sqrt{\lambda m}}\right)$$

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- Requires bounded random variables in QR
- Tradeoff between *n* and *m*
- Mild hypothesis on the kernels

# Numerical experiments: Infinite Quantile Regression

Crossing penalty: hard or soft constraints.

$$\Omega_{\rm nc}(h) := \lambda_{\rm nc} \int_{\mathcal{X}} \int_{\Theta} \left| -\frac{\partial n}{\partial \theta}(x)(\theta) \right|_{+} d\mu(\theta) d\mathsf{P}(x)$$



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Figure 4: Comparison w/o crossing penalty for IQR.

• Matches state of the art on 20 UCI datasets. (Sangnier et al., 2016)

# Numerical experiments: Infinite Cost-Sensitive Classification



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• Improves performances

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#### Figure 5: ICSC vs Independent learning

- Improves performances
- Hard to tune the kernels

# An unsupervised task : Density level set estimation

Integrated problem: minimize in  $h, t \in \mathcal{H}_{K} \times \mathcal{H}_{k_{b}}$ 

$$\int_0^1 \frac{1}{\theta n} \sum_{i=1}^n \max\left(0, t(\theta) - h(x_i)(\theta)\right) - t(\theta) + \frac{1}{2} \|h(\cdot)(\theta)\|_{\mathcal{H}_{k_{\mathcal{X}}}}^2 \mathrm{d}\mu(\theta)$$

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Take  $(\theta_j)_{j=1}^m \in (0, 1)$  a QMC sequence, minimize

$$J(h,t) = \frac{1}{nm} \sum_{i=1}^{n} \sum_{j=1}^{m} \frac{1}{\theta_j} \max(0, t(\theta_j) - h(x_i)(\theta_j))$$
$$- t(\theta_j) + \left\| h(\cdot)(\theta_j) \right\|_{\mathcal{H}_{k_{\chi}}}^2 + \frac{\lambda}{2} \|t\|_{\mathcal{H}_{k_b}}^2$$

There exist  $(\alpha_{ij})_{i,j=1}^{n,m} \in \mathbb{R}^{n \times m}$  and  $(\beta_j)_{j=1}^m \in \mathbb{R}^m$  such that for  $\forall (x, \mathbf{v}) \in \mathfrak{X} \times (0, 1)$ ,

$$h^*(\mathbf{x})(\mathbf{v}) = \sum_{i=1}^n \sum_{j=1}^m \alpha_{ij} k_{\mathcal{X}}(\mathbf{x}, \mathbf{x}_i) k_{\mathbf{v}}(\mathbf{v}, \mathbf{v}_j)$$
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• Weak regularizer but still representer

There exist  $(\alpha_{ij})_{i,j=1}^{n,m} \in \mathbb{R}^{n \times m}$  and  $(\beta_j)_{j=1}^m \in \mathbb{R}^m$  such that for  $\forall (x, v) \in \mathfrak{X} \times (0, 1)$ ,

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## Numerical experiments: Infinite One-Class SVM



**Figure 6:** Level set estimation: the ν-property is approximately satisfied. Top: Wilt benchmark; bottom: Spambase dataset.

Perspectives

• Algorithmic guarantees

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- New regularization term :  $\sum_{j} \|h(\cdot)(\theta_{j})\|_{\mathcal{H}_{k_{Y}}}$

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- Hard monotony constraints
- Scaling up : ORFF (Brault et al., 2016)

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